7.2 The Stationary Matrix

Definition: The **stationary matrix** is written S. It is a state matrix that has the property that SP = S.

Fact: If S exists then $S_k \approx S$ for large values of k.

Example: Let $P = \begin{bmatrix} 0.7 & 0.3 \\ 0.5 & 0.5 \end{bmatrix}$.

a) Check that $S = \begin{bmatrix} 0.625 & 0.375 \end{bmatrix}$ and interpret S.

Check that
$$SP = S$$
.
 $SP = [0.625 \ 0.375] [0.7 \ 0.3]$
 $= [0.625 \ 0.375]$
 $= S$

Once we reach state matrix S, all future state matrices will be S.

b) What will S_{50} look like?

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c) In the distant future, what will the state matrix look like?

S

Comment: If S exists then the Markov chain is sometimes called a regular Markov chain.

Example: Let $P = \begin{bmatrix} 0.9 & 0.1 \\ 0.2 & 0.8 \end{bmatrix}$. Find the stationary matrix.

Let
$$S = [x \ y]$$

Solve $Sl = S$ Logether with $x + y = 1$.

 $Sl = S : [x \ y] [0.9 \ 0.1] = [x \ y]$
 $[0.9x + 0.2y \ 0.1x + 0.8y] = [x \ y]$

$$0.91 + 0.1y = \chi \qquad =) \qquad -0.1x + 0.2y = 0$$

$$0.1x + 0.8y = y \qquad =) \qquad 0.1x - 0.2y = 0$$

$$\chi + y = 1$$

Example Continued...

$$\frac{R_{2}}{-0.3} \begin{cases} 0 & 1 & 1 \\ 0 & 0.3 \\ 0 & 0.3 \end{cases} = \frac{-0.1}{3} \times \frac{10}{10} = \frac{-1}{-3} = \frac{1}{3}$$

$$R_{1} - R_{2} \begin{cases} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{cases} = \frac{2}{3} \begin{cases} -1 - \frac{1}{3} \\ 0 & 1 \end{cases}$$

$$R_{3} - 0.3 R_{2} \begin{cases} 0 & 0 \\ 0 & 0 \end{cases} = 0.1 - 0.3 \left(\frac{1}{3}\right)$$

$$y = \frac{2}{3}$$

$$y = \frac{1}{3}$$

Example: Let
$$P = \begin{bmatrix} 0.7 & 0 & 0.3 \\ 0.5 & 0.5 & 0 \\ 0.3 & 0 & 0.7 \end{bmatrix}$$
. Find the stationary matrix.

Let
$$S = [x] y z]$$

Solve $SP = S$ logether with $x + y + z = 1$
 $SP = S$: $[x y z] \begin{bmatrix} 0.7 & 0.3 \\ 0.5 & 0.5 \end{bmatrix} = [x y z]$
 $[0.7x + 0.5y + 0.3z] = [x y z]$

$$0.71 + 0.5y + 0.3z = 1 \Rightarrow -0.31 + 0.5y + 0.3z = 0$$

$$0.5y = y \Rightarrow -0.5y = 0$$

$$0.31 + 0.7z = 2 \Rightarrow 0.31 - 0.3z = 0$$

$$1 + y + z = 1$$

$$1 + y + z = 1$$

$$0.30.5 = 0.3 = 0$$

$$0.31 + 0.5y + 0.3z = 0$$

$$1 + y + z = 1$$

Example Continued...

$$R_{3} - 0.3R_{1} = \begin{cases} 0 - 0.5 & 0 & 0 \\ 0 - 0.3 & 0.6 & -0.3 \\ 0 - 0.8 & 0.6 & 0.3 \end{cases}$$

$$R_{4} + 0.3R_{1} = \begin{cases} 0 & 1 & 1 & 1 \\ 0 & 1 & 0 & 0 \\ 0 - 0.3 & -0.6 & -0.3 \\ 0 & 0.8 & 0.6 & 0.3 \end{cases}$$

$$R_{1} - R_{2} = \begin{cases} 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0.8 & 0.6 & 0.3 \end{cases}$$

$$R_{3} + 0.3R_{2} = \begin{cases} 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 - 0.6 & -0.3 \\ 0 & 0 & 0.6 & 0.3 \end{cases}$$

$$R_{3} + 0.3R_{2} = \begin{cases} 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0.6 & 0.3 \end{cases}$$

$$R_{3} + 0.8R_{2} = \begin{cases} 1 & 0 & 1 & 1 \\ 0 & 0 & 0.6 & 0.3 \end{cases}$$

$$R_{4} - 0.8R_{2} = \begin{cases} 1 & 0 & 1 & 1 \\ 0 & 0 & 0.6 & 0.3 \end{cases}$$

$$R_{5} - R_{3} = \begin{cases} 1 & 0 & 1 & 0 \\ 0 & 0 & 0.6 & 0.3 \end{cases}$$

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