

Test 1

5 Questions

Covers 1.1-1.4, 2.1-2.2

Tues Sept 23, 1:30-2:20

Bring calculator and music/earplugs

Practice Problems on website

No formula sheet

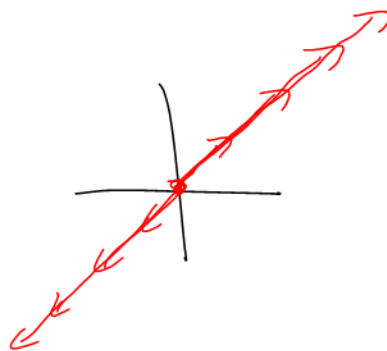
Example: Describe each span geometrically:

a) $\text{span}\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -3 \\ -3 \end{bmatrix}\right)$

$$= \left\{ c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} -3 \\ -3 \end{bmatrix} \right\}$$

$$= \left\{ c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$$

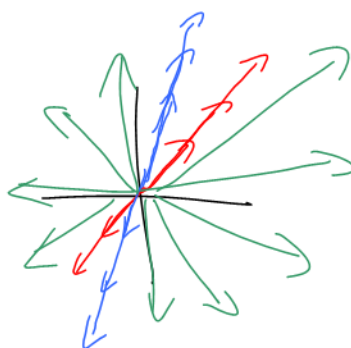
Line in \mathbb{R}^2 through the origin
with $\vec{d} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$.



b) $\text{span}\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix}\right)$

$$= \left\{ c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\}$$

All of \mathbb{R}^2 .

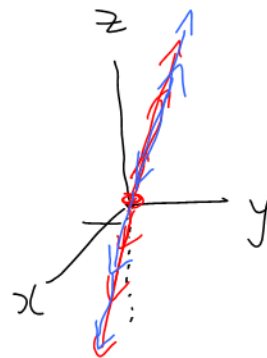


c) $\text{span}\left(\begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} -4 \\ 0 \\ 4 \end{bmatrix}\right)$

$$= \left\{ c_1 \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} + c_2 \begin{bmatrix} -4 \\ 0 \\ 4 \end{bmatrix} \right\}$$

$$= \left\{ c_1 \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \right\}$$

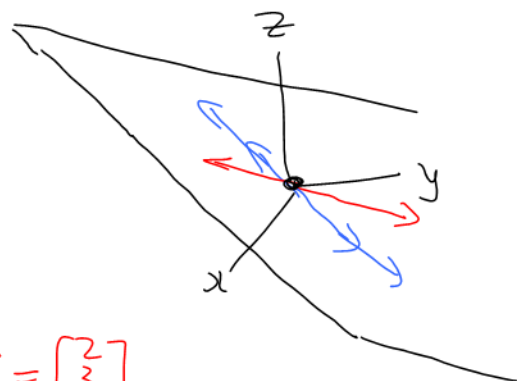
Line in \mathbb{R}^3 through the origin
with $\vec{d} = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$.



d) $\text{span}\left(\begin{bmatrix} 1 \\ 6 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix}\right)$

$$= \left\{ c_1 \begin{bmatrix} 1 \\ 6 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix} \right\}$$

Plane in \mathbb{R}^3 through the origin
with direction vectors $\vec{u} = \begin{bmatrix} 1 \\ 6 \\ 0 \end{bmatrix}$, $\vec{v} = \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix}$



Example: Find an equation for $\text{span}\left(\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \\ 6 \end{bmatrix}\right)$. Give your answer in any form.

It's a plane (in \mathbb{R}^3) through the origin
with direction vectors $\vec{u} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$ and $\vec{v} = \begin{bmatrix} 1 \\ 3 \\ 6 \end{bmatrix}$.

Normal Form

$$\vec{n} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \times \begin{bmatrix} 1 \\ 3 \\ 6 \end{bmatrix} = \begin{bmatrix} -3 \\ -5 \\ 3 \end{bmatrix}$$

$$\begin{array}{|c|c|c|c|c|} \hline 1 & 0 & 1 & 1 & 0 \\ \hline & \times & \times & \times & \\ \hline 1 & 3 & 6 & 1 & 3 \\ \hline \end{array}$$

$$\vec{n} \cdot \vec{x} = \vec{n} \cdot \vec{p}$$

$$\begin{bmatrix} -3 \\ -5 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -3 \\ -5 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \checkmark$$

OR General Form

$$-3x - 5y + 3z = 0 \checkmark$$

OR Vector Form

$$\vec{x} = \vec{p} + s\vec{u} + t\vec{v}$$

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} + s \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + t \begin{bmatrix} 1 \\ 3 \\ 6 \end{bmatrix} \checkmark$$

OR Parametric Form

$$\begin{cases} x = & s + t \\ y = & 3t \\ z = & s + 6t \end{cases} \checkmark$$

Example: a) Show that $\text{span}\left(\begin{bmatrix} 1 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \end{bmatrix}\right) = \mathbb{R}^2$.

$$\text{Let } c_1 \begin{bmatrix} 1 \\ 3 \end{bmatrix} + c_2 \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} a \\ b \end{bmatrix}.$$

Show that this is a consistent system.

$$\begin{bmatrix} c_1 & c_2 & | & a \\ 1 & 2 & | & a \\ 3 & 1 & | & b \end{bmatrix}$$

$$R_2 - 3R_1 \quad \begin{bmatrix} 1 & 2 & | & a \\ 0 & -5 & | & b-3a \end{bmatrix} \text{ REF}$$

The system is solvable
for c_1, c_2 .

b) Write $\begin{bmatrix} a \\ b \end{bmatrix}$ as a linear combination of $\begin{bmatrix} 1 \\ 3 \end{bmatrix}$ and $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$.

$$\text{Let } c_1 \begin{bmatrix} 1 \\ 3 \end{bmatrix} + c_2 \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} a \\ b \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & | & a \\ 0 & -5 & | & b-3a \end{bmatrix}$$

$$\frac{R_2}{-5} \quad \begin{bmatrix} 1 & 2 & | & a \\ 0 & 1 & | & \frac{3a-b}{5} \end{bmatrix} \leftarrow \frac{b-3a}{-5} = \frac{b}{-5} + \frac{-3a}{-5}$$

$$R_1 - 2R_2 \quad \begin{bmatrix} 1 & 0 & | & \frac{-a+2b}{5} \\ 0 & 1 & | & \frac{3a-b}{5} \end{bmatrix} \leftarrow a - 2\left(\frac{3a-b}{5}\right) = a - \frac{6a}{5} + \frac{2b}{5} = -\frac{a}{5} + \frac{2b}{5}$$

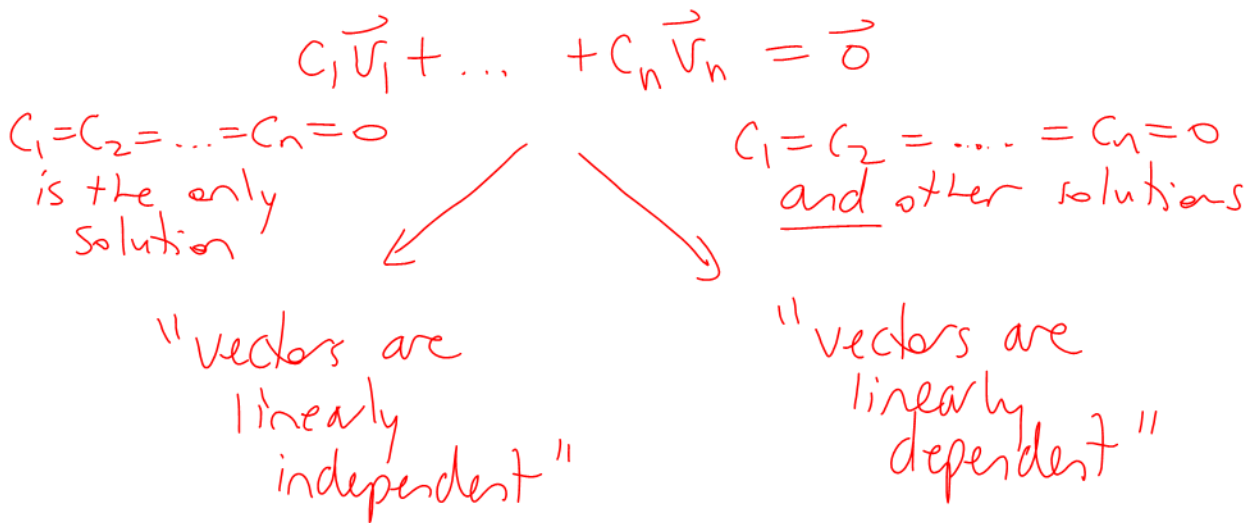
RREF

$$c_1 = \frac{-a+2b}{5} \quad c_2 = \frac{3a-b}{5}$$

$$\boxed{\left(\frac{-a+2b}{5}\right) \begin{bmatrix} 1 \\ 3 \end{bmatrix} + \left(\frac{3a-b}{5}\right) \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} a \\ b \end{bmatrix}}$$

Comment: To decide if a system is ^(solvable) consistent, reduce it to REF.
To solve a system, reduce it to RREF.

Definition: Given $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$, consider solutions to $c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_n\vec{v}_n = \vec{0}$. If the only solution is $c_1 = c_2 = \dots = c_n = 0$ then the set of vectors is **linearly independent**. If there are solutions other than $c_1 = c_2 = \dots = c_n = 0$ then the set of vectors is **linearly dependent**.



Comment: The two sentences below mean the same thing:
Vectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ are linearly independent.
The set $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is linearly independent.

Comment: The two sentences below mean the same thing:
Vectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ are linearly dependent.
The set $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is linearly dependent.