

List of HW Problems and Full Solutions
are on website.

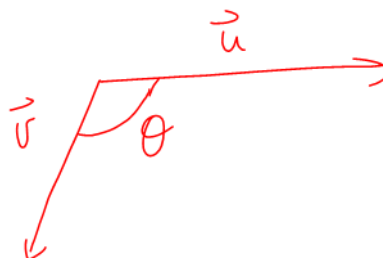
Problems are on D2L.

Do HW for sections 1.1 and 1.2

No formula sheet for Math 251.

nonzero vectors

Fact: Let \vec{u} and \vec{v} be in \mathbb{R}^n . The angle θ between \vec{u} and \vec{v} is defined to be $0^\circ \leq \theta \leq 180^\circ$



Fact: For all \vec{u}, \vec{v} in \mathbb{R}^n : $\vec{u} \cdot \vec{v} = \|\vec{u}\| \|\vec{v}\| \cos \theta$

Comment: In \mathbb{R}^4 and higher dimensions, this is a definition of θ .

Comment: In the special case where \vec{u} and \vec{v} are unit vectors, $\vec{u} \cdot \vec{v}$ gives the value of $\cos \theta$.

Example: Find the angle between $\vec{u} = [1, -4]$ and $\vec{v} = [2, 3]$

$$\begin{aligned}\vec{u} \cdot \vec{v} &= \|\vec{u}\| \|\vec{v}\| \cos \theta \\ -10 &= \sqrt{17} \sqrt{13} \cos \theta \\ \frac{-10}{\sqrt{17} \sqrt{13}} &= \cos \theta \\ \theta &= \cos^{-1} \left(\frac{-10}{\sqrt{17} \sqrt{13}} \right) \\ \theta &\approx 132^\circ\end{aligned}$$

Example: If $0^\circ \leq \theta < 90^\circ$, what is the sign of $\vec{u} \cdot \vec{v}$?

What if $\theta = 90^\circ$?

What if $90^\circ < \theta \leq 180^\circ$?

$$\begin{array}{ccc} 0^\circ \leq \theta < 90^\circ & \left| \begin{array}{c} \theta = 90^\circ \\ \Rightarrow \cos \theta = 0 \\ \Rightarrow \vec{u} \cdot \vec{v} = 0 \end{array} \right| & 90^\circ < \theta \leq 180^\circ \\ \Rightarrow \cos \theta > 0 & & \Rightarrow \cos \theta < 0 \\ \Rightarrow \vec{u} \cdot \vec{v} > 0 & & \Rightarrow \vec{u} \cdot \vec{v} < 0 \end{array}$$

Definition: Vectors \vec{u} and \vec{v} are **orthogonal** if $\vec{u} \cdot \vec{v} = 0$.



Comment: The following statements are equivalent in 2D and 3D:

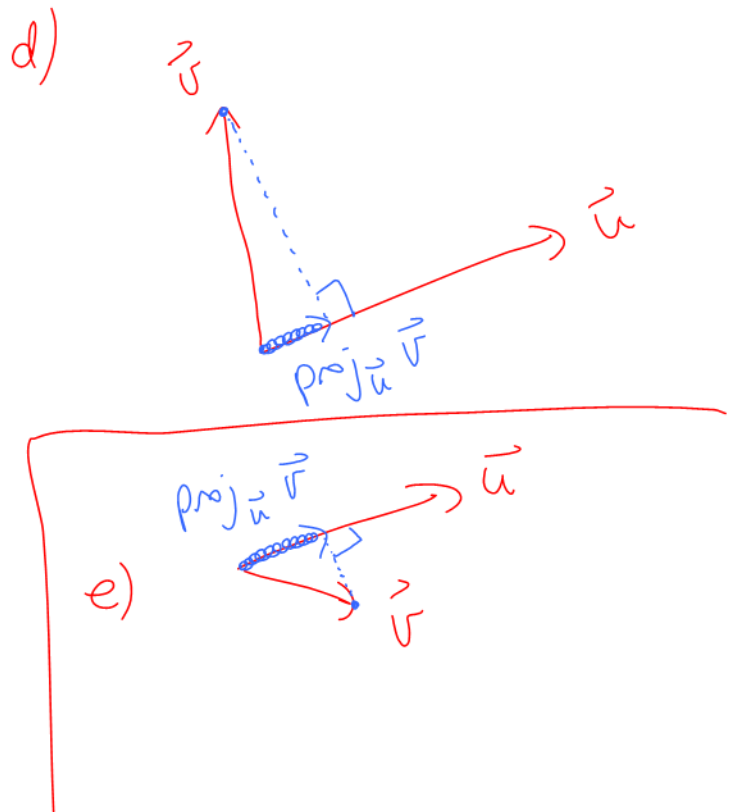
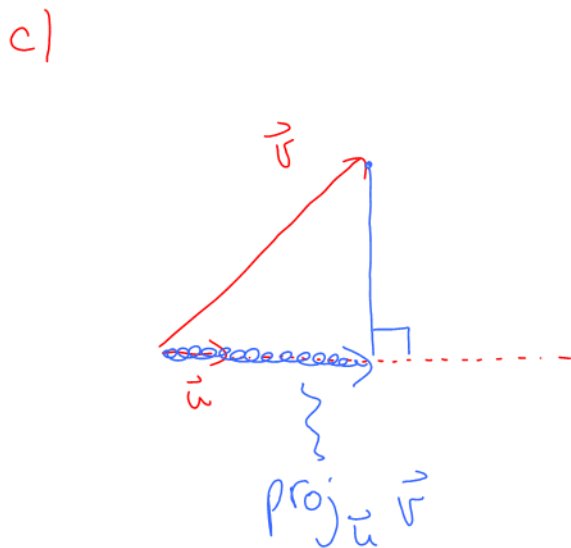
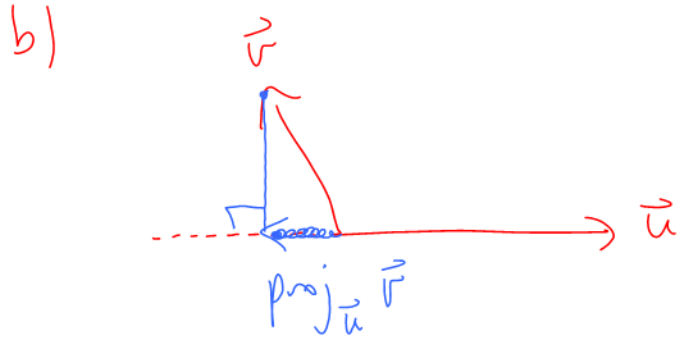
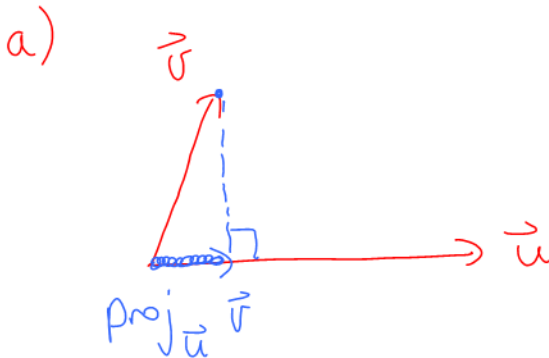
Vectors \vec{u} and \vec{v} are perpendicular (geometry language)

Vectors \vec{u} and \vec{v} are orthogonal (algebra language)

Comment: In higher dimensions it's more appropriate to use the word **orthogonal** rather than perpendicular.

Definition: The **projection** of \vec{v} onto \vec{u} is written $\text{proj}_{\vec{u}}\vec{v}$. This could be read as the projection onto \vec{u} of \vec{v} .

Example: Let's draw a few instances of $\text{proj}_{\vec{u}}\vec{v}$

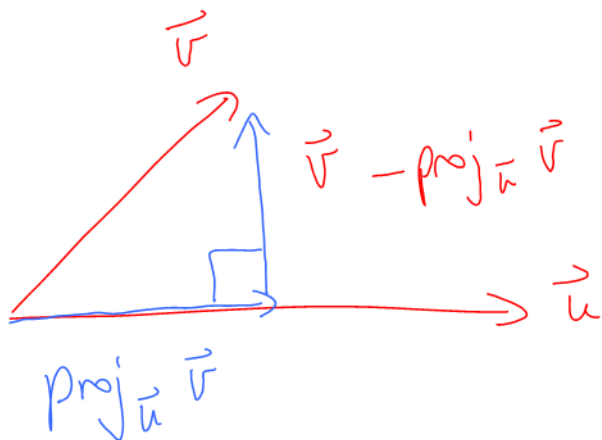


Fact: $\text{proj}_{\vec{u}} \vec{v} = \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\|^2} \vec{u}$

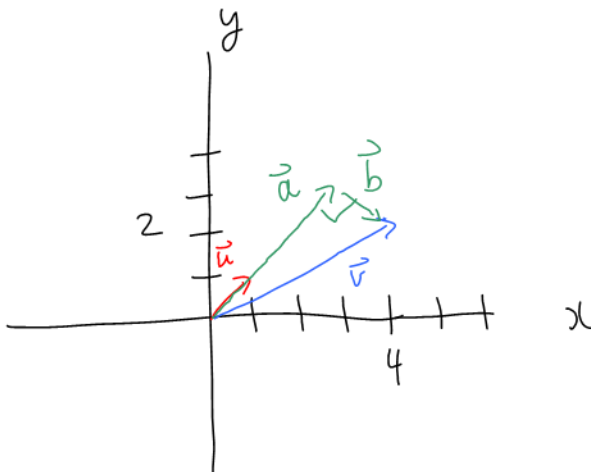
Example: Find $\text{proj}_{\vec{u}} \vec{v}$ for $\vec{u} = [1, 2]$ and $\vec{v} = [1, 3]$

$$\begin{aligned} \text{proj}_{\vec{u}} \vec{v} &= \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\|^2} \vec{u} \\ &= \frac{7}{5} [1, 2] \quad \text{or} \quad \frac{7}{5} \vec{u} \end{aligned}$$

Fact: Given vectors \vec{u}, \vec{v} in \mathbb{R}^n , there is exactly one way to decompose \vec{v} into two vectors that are parallel and perpendicular to \vec{u} .



Example: Let $\vec{u} = [1, 1]$ and $\vec{v} = [4, 2]$. Find vectors \vec{a} and \vec{b} so that $\vec{v} = \vec{a} + \vec{b}$, \vec{a} is parallel to \vec{u} , and \vec{b} is perpendicular to \vec{u} .



$$\begin{aligned}
 \vec{a} &= \text{proj}_{\vec{u}} \vec{v} \\
 &= \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\|^2} \vec{u} \\
 &= \frac{6}{2} [1, 1] \\
 &= 3 [1, 1] \\
 &= [3, 3]
 \end{aligned}$$

$$\begin{aligned}
 \vec{a} + \vec{b} &= \vec{v} \\
 \vec{b} &= \vec{v} - \vec{a} \\
 \vec{b} &= [4, 2] - [3, 3] \\
 \vec{b} &= [1, -1]
 \end{aligned}$$

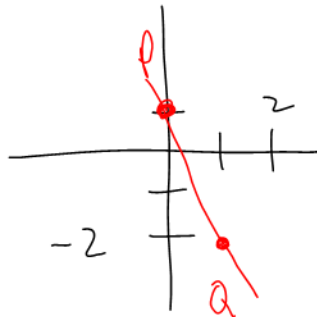
1.3 Lines and Planes

Part 1. Lines in \mathbb{R}^2

Definition: The **general form** of a line in \mathbb{R}^2 is $ax + by = c$

Example: Consider the line $3x + y = 1$. Find two points on the line and graph the line.

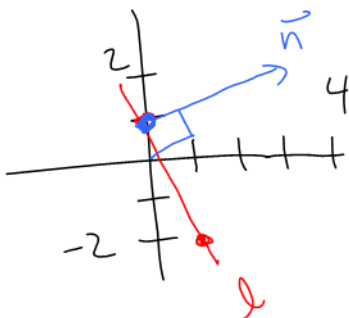
$$\begin{aligned} \text{Set } x=0: & \quad y=1 & P &= (0, 1) \\ \text{Set } x=1: & \quad 3+y=1 & & \\ & \quad y=-2 & Q &= (1, -2) \end{aligned}$$



Definition: A **normal vector** is orthogonal to a given line. It is written \vec{n} . Its components are the coefficients from the general form.



For the line above, $\vec{n} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$



Definition: The **normal form** of a line in \mathbb{R}^2 is $\vec{n} \cdot \vec{x} = \vec{n} \cdot \vec{p}$

where $\vec{x} = \begin{bmatrix} x \\ y \end{bmatrix}$ and \vec{p} is the vectorization of any point on the line.

Example: Describe the line $3x + y = 1$ in normal form. Show that expanding normal form gives general form.

normal form

$$\vec{n} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

$$\vec{n} \cdot \vec{x} = \vec{n} \cdot \vec{p}$$

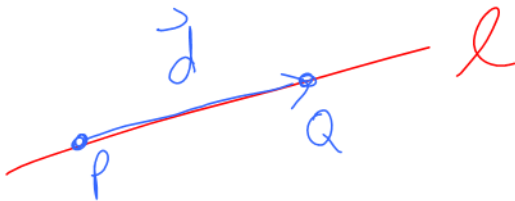
$$\begin{bmatrix} 3 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

any point on the line

general form

$$3x + y = 1$$

Definition: A **direction vector** for a line is $\vec{d} = \overrightarrow{PQ}$, where P and Q are any two points on the line.



Definition: The **vector form** for a line in \mathbb{R}^2 is $\vec{x} = \vec{p} + t\vec{d}$, where t represents any real number.

$$\vec{x} = \vec{p} + t\vec{d}$$

$\vec{x} \rightarrow \begin{bmatrix} x \\ y \end{bmatrix}$
 $t \rightarrow \text{real \#}$
 $\vec{d} \rightarrow \overrightarrow{PQ}$
 $\vec{p} \rightarrow \text{vectorization of any point on the line}$

Example: Describe the line $3x + y = 1$ in vector form. Show that as t varies, the line is traced out.

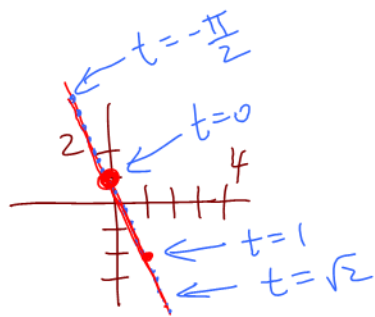
2 points on the line : $P = (0, 1)$
 $Q = (1, -2)$

direction vector $\vec{d} = \vec{PQ}$
 $= \begin{bmatrix} 1 \\ -3 \end{bmatrix}$ Think $Q - P$

Vector form

$$\vec{x} = \vec{P} + t\vec{d}$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} + t \begin{bmatrix} 1 \\ -3 \end{bmatrix}$$



Definition: The **parametric form** for a line in \mathbb{R}^2 is:

$$\begin{cases} x = a + bt \\ y = c + dt \end{cases}$$

Example: Describe the line $3x + y = 1$ in parametric form.

vector form $\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} + t \begin{bmatrix} 1 \\ -3 \end{bmatrix}$

Expand: $\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} + \begin{bmatrix} t \\ -3t \end{bmatrix}$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} t \\ 1-3t \end{bmatrix}$$

parametric form $\begin{cases} x = t \\ y = 1-3t \end{cases}$

Comment: A given line can be described in a specific form in multiple ways, for example $3x + y = 1$ and $6x + 2y = 2$ are general forms for the same line.

Example: Summarize the four forms of a line in \mathbb{R}^2

General Form

$$3x + y = 1$$

Normal Form

$$\vec{n} \cdot \vec{x} = \vec{n} \cdot \vec{p}$$

$$\begin{bmatrix} 3 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

Vector Form

$$\vec{x} = \vec{p} + t\vec{d}$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} + t \begin{bmatrix} 1 \\ -3 \end{bmatrix}$$

Parametric Form

$$\begin{cases} x = t \\ y = 1 - 3t \end{cases}$$